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Johnson Space Center-Houston, Texas

**Engineering Prototype** Failure Environment **Analysis Tool (FEAT** Development:

**Automation and Robotics Division** D.G. Lawler/ER22

8/8/91

# ENGINEERING PROTOTYPE DEVELOPMENT

Failure Environment

Analysis Tool (FEAT)

**Advanced Automation Section** D. G. Lawler, ER22 Section Head August 8, 1991





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## DEVELOPMENT BACKGROUND

# SPACE SYSTEMS FAILURE ANALYSIS:

- Several approaches used by NASA SRM&QA, e.g.:
- Failure Modes and Effects Analysis/Critical Items
- Integrated Hazards Analysis
- Digraph Modeling:
- Developed in late 60's for nuclear power systems
- Supports existing analysis methods
- Supports Fault Tolerance and Redundancy Mngt Analysis



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### NOTES FOR PAGE I OF: DEVELOPMENT BACKGROUND

- · Detailed understanding of the nature and extent of failures within an engineered system is absolutely vital for the successful deployment of such systems.
- probability of system failures, the nature of these failures, the effect of these failures on other Current NASA practice employs a number of different analysis techniques to determine the system components and the ultimate consequence of these failures on safety and overall mission effectiveness.
- Typical of these analyses are the Failure Modes and Effects Analysis/Critical Items List and the Integrated Hazards Analysis.
- technique called Digraph Matrix Analysis was developed from work done at Lawrence Livermore In response to the need for a detailed understanding of system failures and their effects, a National Laboratories on nuclear reactor safety analysis.
- boolean -and- gates to model the propagation of failures throughout a system; both working This technique utilizes a directed graph modeling technique extended with the use of simple from initial failure to final consequence as well as the reverse case.
  - Such a technique is very useful in determining the effectiveness of the fault tolerance and redundancy management in the system's design.

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## DEVELOPMENT BACKGROUND (cont'd)

## **FEAT PROJECT HISTORY:**

- Shuttle use of digraphs began in 1988
- FEAT development began in 1989
- Early general release in 1990
- FEAT version 3.3. currently available
- SSFP directive for digraph use issued 7/91



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## NOTES FOR PAGE 2 OF: DEVELOPMENT BACKGROUND

- Use of the digraph technique for modeling STS systems began in 1988 under the STS ntegration contract with Rockwell.
- Modelers soon realized the need for software to ease the burden associated with both modeling and the analysis of the model.
- FEAT development began in 1989, sponsored by C. Vaughan, Chief of the NASA JSC Propulsion and Power Division.
- selected failures. It also displays the possible initial failures for user selected conditions. FEAT operates on an Apple Macintosh II computer and displays in color the effects of user Selection and display can be on either the digraph or a system schematic.
- FEAT has the capability to handle very large, orbiter size models. It includes the capability to reconfigure the digraph and schematic by preselecting numerous failures as having occurred, and then observing the causes and effects of additional failures.
  - Sponsorship of FEAT was shifted to Automation & Robotics in the fall of 1990, with funding from the SSFP.
- The Digraph Editor was released in the spring of 1991 to assist in building models.
- methods be utilized for support of Integrated Failure Modes and Effects Analysis, Integrated Hazards Analysis and Fault Tolerance and Redundancy Management Analysis. He also In July 1991, R. Moorehead (director of SSFP/Level II) directed that Digraph modeling directed that FEAT be used for this support.

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## DEVELOPMENT BACKGRÖUND (cont'd)

#### **OBJECTIVE:**

techniques to better understand and capture the flow of failures within and between elements of SSF and To demonstrate advanced modeling and analysis other large complex systems

## TECHNICAL CHALLENGE:

- Provide efficient modeling and analysis capabilities
- Capture system failure knowledge for use throughout program lifecycle
- Integrate into other applications and environments



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### NOTES FOR PAGE 3&4 OF: DEVELOPMENT BACKGROUND

- · This project is being pursued to enable SSFP managers to capture the flow of failure effects from within each element out to other elements, including those of the international
- determination of the set of potential failures which are the most likely to have caused a Successful completion of this project will provide a capability to quickly and efficiently predict effects from multiple failures in different station elements. It will also permit given set of observed effects.
- FEAT will provide a means to demonstrate compliance with fault tolerance and redundancy requirements in a highly efficient manner. Also, design decisions can be affected by information available through FEAT and presented during design reviews.
- and Mission Operations support personnel with equal capability to determine the answers to "What if . . . ?" questions. When discussing issues, all of these organizations will be The model in FEAT will provide Engineering, Safety, Reliability, Supportability, Training, utilizing the same data set for these analyses.

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## DEVELOPMENT BACKGROUND (cont'd)

## **BENEFITS/APPLICATIONS:**

- Support for SRM&QA analyses of large complex systems
- Increase systems reliability and systems safety
- Enables the comprehensive analysis of large complex systems
- Capture of system failure knowledge
- Support for engineering design (e.g. system evolution) training, operations, etc.
- Cost savings from maintenance of single data source



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## **TECHNICAL APPROACH**

#### **OVERVIEW:**

- Develop base capabilities on Macintosh
- FEAT & Digraph Editor
- Port identical capability to Unix and X-Windows environments
- Integrate into TMIS environment
- Support modeling activities
- STS (e.g. MMU) & SSFP systems
- Support additional digraph applications



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#### NOTES FOR PAGE 1 OF: TECHNICAL APPROACH

- operating system computers supporting the X Window interface environment, including the SSFP TMIS standard intergraph CIE workstation. All coding is in the K&R C programming language. There is no PC version in development or planned at this time. Macintosh versions of FEAT are being produced first. The code is then ported to Unix
- All machines running the same version of FEAT will have the same look and feel to the user.
- forwarded to COSMIC. This will provide the basic functionality required to begin modeling At the end of August 1991 FEAT 3.3 and the Digraph Editor 3.0 will be released and Freedom and to analyze the resultant models.
- Model development is currently being funded separately from the software enhancement



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## SSFP BASELINE INTEGRATION

### GENERAL SUPPORT:

- Level III funding near term analysis support needs
- Level I funding advanced development efforts

#### **SSFP LEVEL II:**

- Digraphs and FEAT have been adopted for supporting Integrated FMEA, Integrated Hazards Analysis, etc.
  - Support for MTC Phase Review and CDR

### **SSFP OPERATIONS:**

- Support for SSCC Fault Detection and Management function (under consideration, decision by 1/92)
  - Support for SSFP & STS training script development (under consideration)



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## NOTES FOR PAGE 1 OF: SSFP BASELINE INTEGRATION

- Engineering at JSC, is funding the features needed in the near future to support Program FEAT project funds are provided are by SSFP Levels I and II. decision points.
- Level I is funding capability development to support needs required later in the Program.
- New versions of FEAT will support FMEA development and be integrated with the SSF TMIS.
- Initial Freedom modeling will focus on areas with the greatest payback in design evaluation at the MTC CDR.
- Digraphs and schematics in FEAT will support needs of at a minimum the following organizations:
- Program Engineering (including design engineering integration, safety, reliability, and supportability)
- Mission Operations (including training and mission support)



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## **GROWTH AND EVOLUTION**

## **FEAT ENHANCEMENTS:**

- Integration of FEAT with other SRM&QA tools
- Digraph Editor enhancements
- Large model processing

## **ADVANCED DEVELOPMENT:**

- Smart Digraph Editor will provide automated support to model development
- Advanced modeling support
- · e.g. Temporal modeling and analysis



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#### NOTES FOR PAGE 1 OF: GROWTH AND EVOLUTION

- Enhancements to FEAT are being pursued by SSFP Levels I and II. Level II, through level III Engineering at JSC, is funding the features needed in the near future to support Program decision points.
- Level I is funding capability development to support needs required later in the Program.
- This includes support of the Space Station Control Center Fault Detection and Management capability, as well as a Smart Digraph Editor to reduce the manpower intensity of digraph modeling.
- Large model analysis is very expensive computationally. Parallel processing capability is being developed to significantly reduce the turn-around time required for transitive closure calculations.



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#### SUMMARY

- FEAT is available now and in use by SSFP
- Robust, ongoing, development program
- Many significant potential applications
- Significant cost avoidance/savings anticipated through use of common models



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## NOTES FOR PAGE 1 OF: SUMMARY

effects across Freedom, but the broad application of advanced modeling techniques is only now becoming understood within the NASA community. Significant cost savings undergoing continuous improvement. It will be used to assist in the analysis of failure is anticipated through the use of common models over a broad range of applications. FEAT is available now to support various types of engineering applications and is